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Control over the supply and movement of materials is now keenly sought.

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give flexibility in sequence and quantity. None of these objectives for improved performance is entirely a technical matter, although there is an increasing technical ability to influence all of them.

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This applies at all levels, and the availability of people

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with competence in

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Driven Parallel

Robots, this book covers classification and definition,

kinematics, workspace analysis,

cable modeling, hardware/prototype development, control

and calibration and more.

A comprehensive survey of the growing

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field of self-robots  
reconfigurable robots  
that discusses the  
history of the field,  
design behavioural  
considerations, and  
control strategies. Self-  
reconfigurable robots  
are constructed of  
robotic modules that  
can be connected in  
many different ways.  
These modules move  
in relationship to each

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other, which allows the robot as a whole to change shape. This shapeshifting makes it possible for the robots to adapt and optimize their shapes for different tasks. Thus, a self-reconfigurable robot can first assume the shape of a rolling track to cover distance quickly, then the shape of a snake

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to explore a narrow space, and finally the shape of a hexapod to carry an artifact back to the starting point.

The field of self-reconfigurable robots has seen significant progress over the last twenty years, and this book collects and synthesizes existing research previously only available in

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widely scattered individual papers, offering an accessible guide to the latest information on self-reconfigurable robots for researchers and students interested in the field. Self-Reconfigurable Robots focuses on conveying the intuition behind the design and control of self-



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reconfigurable robots rather than technical details. Suggestions for further reading refer readers to the underlying sources of technical information. The book includes descriptions of existing robots and a brief history of the field; discussion of module design considerations,

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including module geometry, connector design, and computing and communication infrastructure; an in-depth presentation of strategies for controlling self-reconfiguration and locomotion; and exploration of future research challenges.

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Using the case of an industrial accident involving a killer robot, the author successfully combines technical and ethical concepts to present to students and professionals real-life issues that they may one day have to confront.

Begins with the most

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fundamental, plain-  
English concepts and  
everyday analogies  
progressing to very  
sophisticated  
assembly principles  
and practices.

Examples are based  
on the 8086/8088  
chips but all code is  
usable with the entire  
Intel 80X86 family of  
microprocessors.

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and MASM. Gives  
readers the  
foundation necessary  
to create their own  
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been the essential  
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oriented technology,  
which, in turn, has

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authors draw upon  
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experience to offer  
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readers--with five chapters that each delve into one phase of the overall development lifecycle. Fresh approaches to reasoning about complex systems An examination of the conceptual foundation of the widely misunderstood fundamental elements of the object model,

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such as abstraction, encapsulation, modularity, and hierarchy How to allocate the resources of a team of developers and manage the risks associated with developing complex software systems An appendix on object-oriented programming languages This is the

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seminal text for anyone who wishes to use object-oriented technology to manage the complexity inherent in many kinds of systems.

Sidebars Preface

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Having edited  
"Journal of Materials  
Processing  
Technology"  
(previously entitled  
"Journal of

Mechanical Working  
Technology") for close  
on 25 years, I have  
seen the many  
dramatic changes that  
have occurred in the

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materials processing field. Long gone are the days when the only "materials processing" carried out was virtually the forming of conventional metals and alloys, and when the development of a new product or process in a great number of cases called for several



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months of repetitive trial-and-error,' with many (mostly intuition- or experience-based) expensive and time-consuming modifications being made to the dies, until success was achieved. Even when a 'successful' product was formed, its mechanical

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properties, in terms of springback and dimensional accuracy, thickness variations, residual stresses, surface finish, etc., remained to be determined. Bulk-forming operations usually required expensive machining to be carried out on the product to impart the required

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dimensional accuracy  
and surface finish.

Over the years, the  
experience-based  
craft of metal forming  
has given way to the  
science of materials  
processing. With the  
use of the computer,  
forming operations  
can be simulated with  
accuracy, to

determine the best  
forming route and the

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